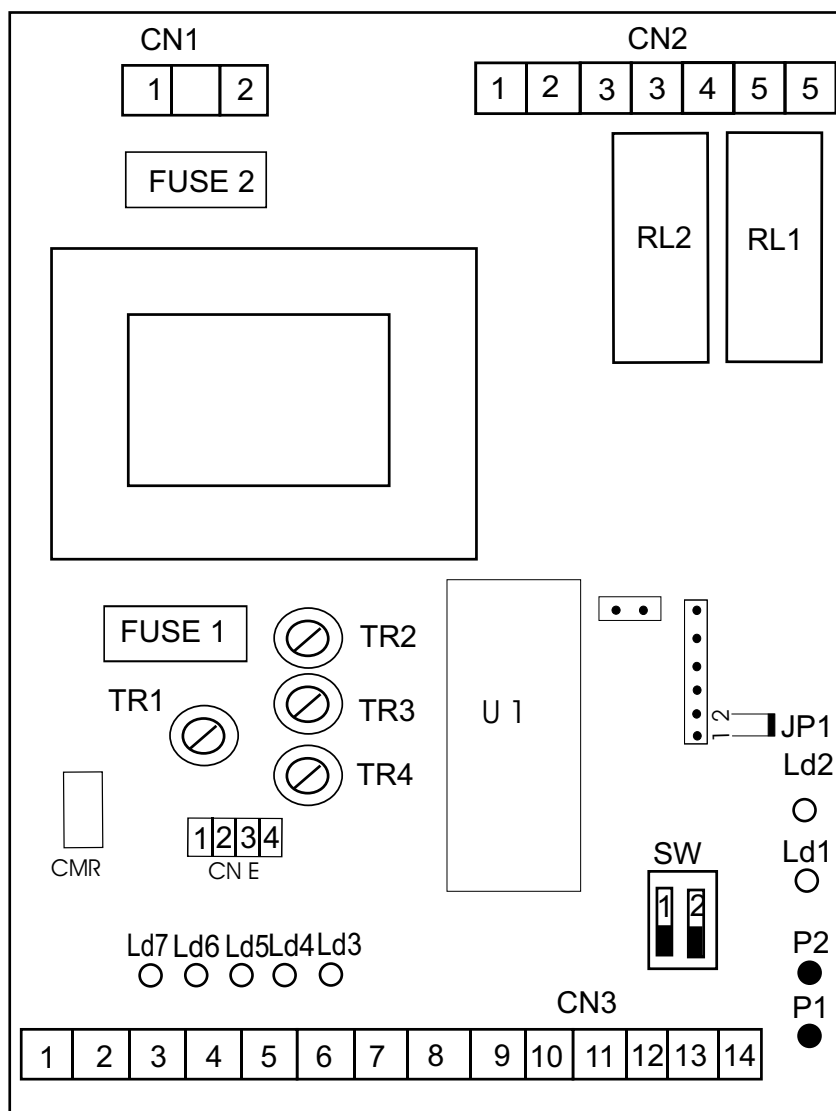




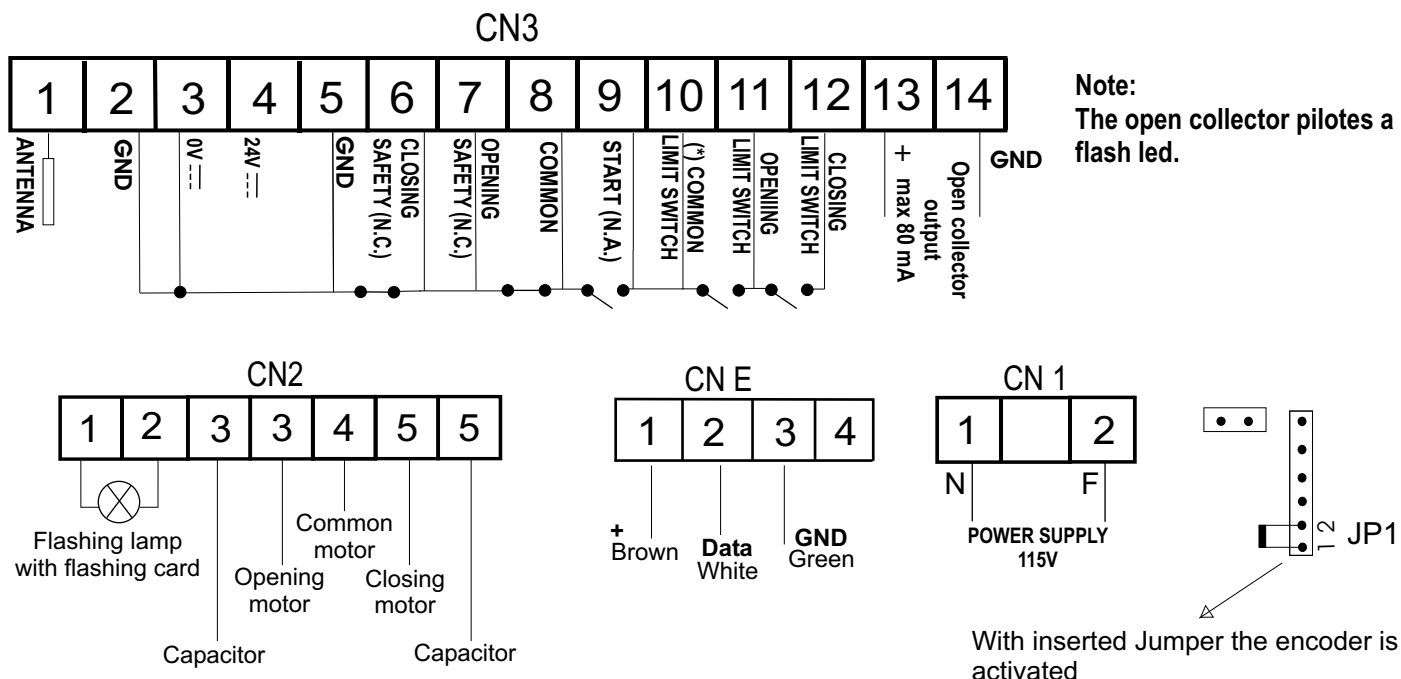
## SLIDE NEW MAG CONTROL BOARD



FUSE 1	Fuse 24V=== (2A)
FUSE 2	Fuse 115V~ (10A)
TR1	Automatic closing adjustment (0 s - 4 min.)
TR2	Motor torque adjustment
TR3	Ped. Opening time adjustment
TR4	Brake adjustment
SW.1	Logic
SW.2	Closing with photocell
RL 1	Motor direction relay
RL 2	Motor enabling relay
CN 1	Power supply 115V~ connector
CN 2	Motor connector - flashing light/courtesy light

CN 3	Accessories connector
CMR	Radio receiver connector
CN E	Encoder connector
LD1	Times/remote controls
LD2	Times/remote controls
LD3	Limit switch 1LED
LD4	Limit switch 2 LED
LD5	Start LED
LD6	Opening safety LED
LD7	Photocell LED
JP1	Encoder activation
U1	Micro-controller
P1	Programming buttons
P2	Programming buttons

## ELECTRIC CONNECTIONS



**Note1:** When not used, bridge the N.C. contacts of safety in opening and/or of the photocell.

**Note2:** Output 24V, max 200mA.

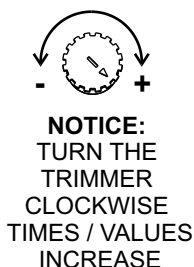
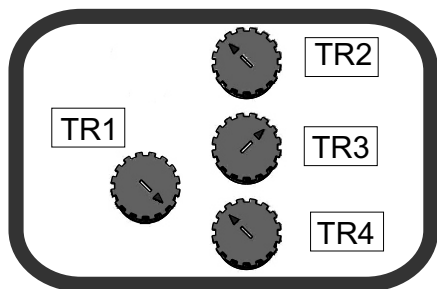
**Security management:** If the security opening command is busy during opening the gate recloses immediately. The command is not active in closing when the safety command (in closing) is busy during closing, the gate reopens. The command is not active in opening.

If the two safeties are both active, the gate will not move and a start command will start it again. The gate will restart in the opposite direction to the last engaged safety.

**Attention:** The motor comes without anti-squeezing security device, it is necessary to use photocells and security edges.



## TRIMMER SETTINGS



### **TR1. Trimmer: Automatic reclosing time (0:4 min.)**

It allows to set the pausing time from 0 to 4 min. With trimmer on 0 the logic will be semi-automatic, turning the trimmer clockwise the logic becomes automatic.

### **TR2. Trimmer: Motor torque setting**

Turn the Trimmer completely into clockwise direction for maximum torque.

### **TR3. Trimmer: Pedestrian opening setting**

For pedestrian opening time setting from 0 to 15s.

### **Tr4 Trimmer: Braking on limit switch setting**

For braking force on limit switch setting.

**Note:** It is very important to set the brake in function of the set torque. If the value of the torque decreases, it is necessary to increase the braking value turning the trimmer clockwise.

## DIP SWITCHES SETTING

1	ON	Open-Stop-Close-Open logic	See Step-by-step logic
1	OFF	Automatic/semi-automatic logic (depends on the trimmer setting)	See automatic and semi-automatic logic
2	ON	Reclosure with activated photocell	If the DIP SW 2 is on, the gate will close automatically 2 seconds after having passed the photocell.
2	OFF	Reclosure with disactivated photocell	

## WORKING TIME PROGRAMMING

### **Selflearning of the working times with limit switch**

- 1) Put the gate on halfway.
- 2) Keep pressed P1 for three seconds, until the LEDs 1 and 2 blink alternately, at this point press P2 and release the two buttons.
- 3) Make sure that the automation starts closing. If the limit switch of closing has been read, the automation does not start automatically in opening again, reverse the limit switches and repeat the selflearning from step 1.
- 4) If the automation starts properly, it will execute automatically a CLOSE-OPEN-CLOSE cycle and will end the learning of the times.



## WORKING LOGICS DESCRIPTION

### **Logic with automatic reclosure from 10 seconds to 4 minutes (Trimmer TR1 turned clockwise):**

A start impulse opens the gate, a start impulse in opening is not accepted, a start impulse during the pausing time closes the gate, a start impulse in closing reopens the gate.

### **Semiautomatic logic (Trimmer TR 1 turned completely counterclockwise):**

A start impulse opens the gate, a start impulse in opening stops the movement, the following impulse opens the gate. A start during pause recloses the gate, a start impulse in closing reopens it.

### **Pedestrian logic (only from radio transmitter)**

A pedestrian start impulse provokes the pedestrian opening. At the end of the pausing time the gate will reclose automatically.

In semiautomatic logic a pedestrian start is necessary to reclose the gate. A pedestrian start during the pedestrian opening reopens the gate. A start during pedestrian pause provokes the total opening.

### **Automatic step-by-step logic can be set from 10 seconds to 4 minutes (TR1 Trimmer turned clockwise)**

The start command follows the OPEN-STOP-CLOSE-OPEN logic.

The automation recloses automatically at the end of the pausing time.

### **Semiautomatic step-by-step logic (TR 1 Trimmer turned completely counterclockwise):**

The start command follows the OPEN-STOP-CLOSE-OPEN logic.

During pause a start impulse is necessary to reclose the gate.

### **Timer function**

It is possible to obtain the timer function keeping busy the start input and setting the automatic reclosure. The gate will close as soon as the contact becomes N.O. again.

### **Encoder Administration**

The encoder allows to obtain the inversion of movement on obstacles. In case of obstacles in both closing and opening the gate will completely reverse. At the next start impulse the gate will start in the opposite direction to the one in which it has revealed the obstacle. If in automatic logic the gate tries to restart for 3 times, at the fourth time it will remain open and the warning lamp will remain switched on. After the fourth consecutive intervention it will be necessary to give a start impulse to restore the movement.

Note: The inversion on obstacle will be controlled till the limit switch has been reached.

### **Attention:**

**In case of no power supply with activated limit switch and Encoder the first movement will be made without inversion control on obstacle, till the limit switch in opening has been reached.**



# RADIO TRANSMITTERS PROGRAMMING



**WARNING:** Make the radio transmitters programming before you connect the antenna and insert the receiver into the special CMR connector (if available) with turned off control unit. (The control unit automatically recognizes if the receiver is a RF, RF Roll, RF Roll Plus or RF UNI module).

With RF Roll or RF Roll Plus module it will be possible to use only Coccinella Roll or Coccinella Roll Plus radio transmitters. or Smart Dual Roll or Smart Dual Roll Plus.

With the RF UNI module it will be possible to use both the transmitters of the Roll Plus series and those with fixed code. The first memorized transmitter determines the type of the remaining radio transmitters.

## Notes:

- Enter radio transmitters learning only when the working cycle stops and the gate is closed.
- If the radio transmitters are Rolling Code or Rolling Code Plus it's possible to memorize up to 800 codes (buttons).
- If the radio transmitters are with fixed code it will be possible to memorize up to max. 30 codes (buttons).

**Note 2:** On all RF models, the HEAD transmitters are stored as fixed code.

## Selflearning of the radio transmitter Start

- 1) Press P2 for 3 seconds, LEDs 1 and 2 will flash alternately.
- 2) Press P1 to select LED1, afterwards press P2 (LED1 stays turned on) to confirm the choice and press the button of the radio transmitter to which you want to assign the start. LED 1 switches off, signal has been learned.

## Selflearning of the pedestrian start from radio transmitter

- 1) Press P2 for three seconds, leds 1 and 2 will flash alternately.
- 2) Press P1 twice, to select LED2, afterwards press P2 (LED2 stays turned on) to confirm the choice and press the button of the radio transmitter to which you want to associate the pedestrian start. LED1 switches off, signal has been learned.

## Erasing of all transmitters

- 1) Press P2 for three seconds, the LEDs 1 and 2 will flash alternately.
- 2) Keeping pressed P1, press the P2 button for three times.



## **SAFETY PRECAUTIONS**

Every change on trimmers and on dip switch must be done with the gate closed, or without power supply.

All electrical installation work should conform to the current edition of the LEE Regulations and all electrical work should only be carried out by a competent electrician. A 16A - 0,03A differential switch must be incorporated into the mains electrical supply of the gates. Earth bonding of the entire gate system must be correctly carried out.

To prevent mains interference all low voltage cabling (Push button, Photocell, Radio etc.) should be run in separate cable ducts from main carrying cables.

Note: Use "cable clips" and/or "duct/box pipes" fitting close to the control panel box so to protect the interconnection cables against pulling efforts.

## **SPARE PARTS**

To obtain spare parts contact:

**SEA USA Inc. 10850 N.W. 21st unit 160 DORAL MIAMI Florida (FL) 33172 USA**  
**Phone:++1-305.594.1151 Fax: ++1-305.594.7325 Toll Free: 800.689.4716**  
**E-mail: sales@sea-usa.com**

## **INTENDED USE**

The SLIDE electronic control unit has been designed to be solely used as control unit for the automation of sliding gates.

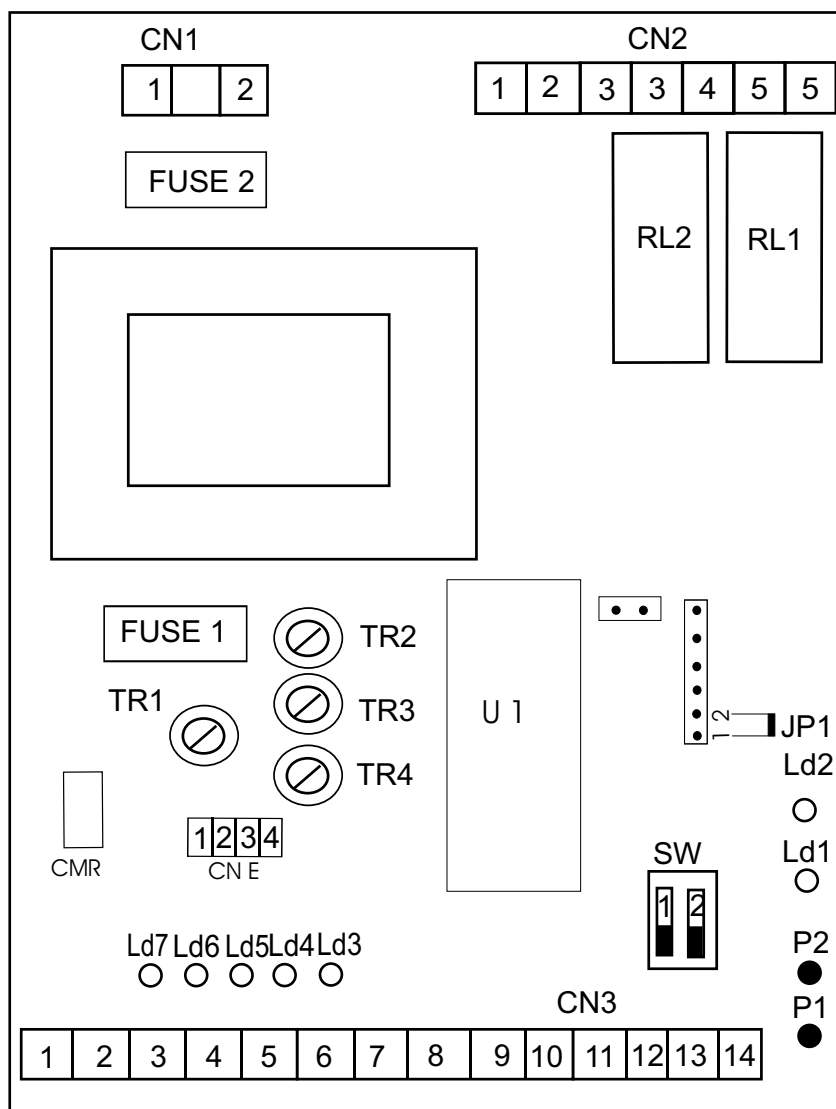
## **LIMIT OF GUARANTEE**

For the guarantee see the sales conditions on the official SEA price list.

**NOTE: THE MANUFACTURER CAN NOT BE DEEMED RESPONSIBLE FOR ANY DAMAGE OR INJURY CAUSED BY IMPROPER USE OF THIS PRODUCT.**



## APARATO ELECTRÓNICO SLIDE MAG

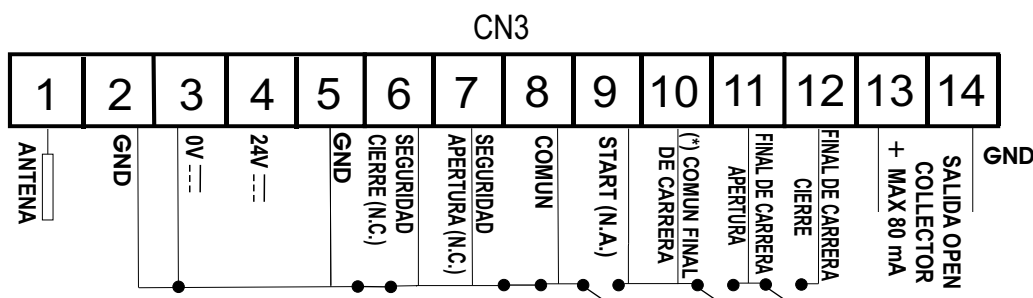


FUSE 1	Fusible 24V--- (2A)
FUSE 2	Fusible 115V~ (10A)
TR1	Regulación cierre automático (0 s - 4 min.)
TR2	Regulacion cupla motor
TR3	Regul. Tiempo de ap. Peat.
TR4	Regulación frenada
SW.1	Lógica
SW.2	Cierre con fotocélula
RL 1	Relé dirección motor
RL 2	Relé activación motor
CN 1	Conector alimentación 115V~
CN 2	Conector motor - lampara/luz de cortesía

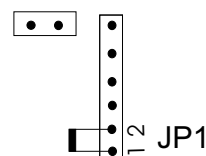
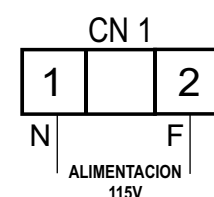
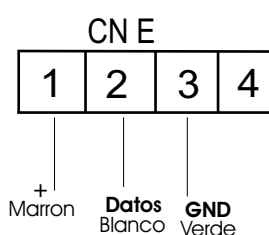
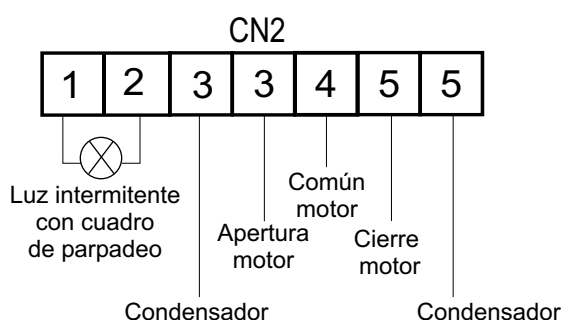
CN 3	Conector accesorios
CMR	Conector receptor de radio
CN E	Conector Encoder
LD1	Progr.tiempo/radiocomandos
LD2	Progr.tiempo/radiocomandos
LD3	Led de final de carrera 1
LD4	Led de final de carrera 2
LD5	Led de start
LD6	Led seguridad apertura
LD7	Led fotocelula
JP1	Activación Encoder
U1	Microcontrollore
P1	Botones de programación
P2	Botones de programación



## CONEXIONES ELECTRICAS



Nota:  
La salida "open collector" pilotará una bombilla Flash led.



Con Jumper insertado se activa el Encoder

**Nota 1:** Si no son utilizados, puentear lo contactos normalmente cerrados de la Seguridad en apertura y/o de la fotocélula.

**Nota2:** salida 24V, max 200mA

**Gestión seguridad:** el mando Seguridad apertura si empuñado durante el apertura provoca el cierre inmediato. El mando no está activo en cierre.

El mando Seguridad cierre si empuñado durante el cierre provoca la reapertura de la cancela. El mando no está activo en apertura.

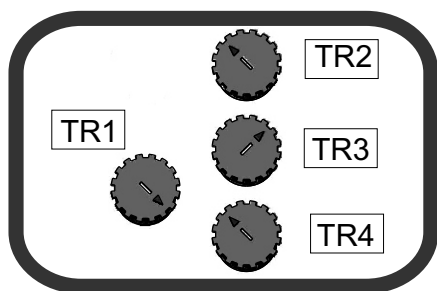
Si las dos seguridades resultan ambas activas, la cancela quedará parada y será necesario un mando de start para hacer repartir la cancela.

La cancela repartirá en el verso opuesto a la última seguridad empuñada.

**Atención:** el motor está desprovisto de seguridades anti-aplastamiento, es necesario el utilizo de fotocélulas y costas de seguridad.



## REGULACION TRIMMER Y DIP SWITCHES



### **TR1. Trimmer Tiempo de cierre automático (0:4 min.)**

Este Trimmer permite la regulación del tiempo de pausa en un intervalo que puede asumir todos los valores incluidos entre 0 s y 4 min. Con trimmer a 0 la lógica resulta semiautomática, girando el trimmer en sentido horario, la lógica se pondrá automática.

### **TR2. Trimmer regulacion de la cupla**

Este trimmer permite regular la cupla del motor, Trimmer todo en sentido retrógrado, cupla máxima.

### **TR3. Trimmer de regulación abertura peatonal**

Regulará el tiempo de abertura peatonal entre 0 y 15 s.

### **TR4. Trimmer por la regulación de la frenada sobre el fin de carrera**

Regla la fuerza de frenada sobre el fin de carrera.

**Nota: es muy importante que se ajuste la frenada en función de la regulación de la cupla. Si se reduce el valor de la cupla es necesario subir la frenada girando el trimmer TR4 en sentido horario.**

## POSICIÓN DIP SWITCHES

1	ON	Lógica abre-stop-cierra-abre	Ver lógica Paso Paso
1	OFF	Lógica automática/semiautomática (según la fijación del trimmer)	Ver lógica Automática e Semiautomática
2	ON	Richiusura con fotocellula abilitata	Si el dip sw está en ON al cruzar la fotocelda después dos segundos habrá el cierre automático.
2	OFF	Richiusura con fotocellula disabilitata	

## PROGRAMACIÓN TIEMPOS DE TRABAJO

### **Autoaprendizaje de los tiempos de trabajo con final de carrera**

- 1) Poner la automación a medias corrida.
- 2) Tener comprimido P1 por tres segundos, hasta que los led 1 y 2 no relampagueará alternativamente, a este punto comprimir P2 y conceder los dos interruptores.
- 3) Observar que la automación parta en cierre. Si leyera el final de carrera de cierre la automación no reparte automáticamente en abertura, invertir los finales de carrera y repetir el autoaprendizaje del punto 1.
- 4) Si la automación reparte correctamente ira ejecutando un ciclo CIERRA-ABRE-CIERRA y acabará el aprendizaje de los tiempos.

## DESCRIPCION LOGICA DE FUNCIONAMIENTO

### **Lógica con cierre automático arreglable de 10 segundos hasta 4 minutos (Trimmer TR1 rodeado en sentido horario)**

Un impulso de start abre la cancela, un start en apertura no viene aceptado, un start en pausa cierra, un start en cierre vuelve abrir.

### **Lógica semiautomática (SW1 en OFF) (Trimmer TR1 todo en sentido anti-horario):**

Un impulso de start abre la cancela, un start en abertura para el movimiento, el siguiente abre. Un start en pausa cierra la cancela un start en cierre vuelve abrir.

### **Lógica Peatonal (sólo de radiocomando):**

Un impulso de start peatonal provoca la abertura peatonal, acabado el tiempo de pausa se obtiene el cierre automático del peatonal.

En lógica semiautomática será necesario un start peatonal para cerrar la automatización. Un impulso de start peatonal durante la abertura peatonal reabre el peatonal. Un impulso de start durante la pausa peatonal, provoca la abertura total.

### **Lógica paso paso automática arreglable de 10 segundos hasta 4 minutos (Trimmer TR1 rodeado en sentido horario)**

El mando de start sigue la lógica ABRE-STOP-CIERRA-ABRE.

Al acabarse el tiempo de pausa el automatismo va a cerrar automáticamente.

### **Lógica paso paso semiautomática (Trimmer TR1 todo en sentido anti-horario):**

El mando de start sigue la lógica ABRE-STOP-CIERRA-ABRE.

En pausa será necesario un impulso de start para cerrar el automatismo.

### **Función temporizador**

Es posible conseguir la función temporizador al tener empeñado la entrada de start y programando el cierre automático. La cancela cerrará en cuanto el contacto vuelve N.O.

### **Gestión Encoder**

El Encoder permite de conseguir la inversión del movimiento sobre obstáculo. En caso de obstáculo sea en cierre que abertura hay la inversión total del movimiento. Al start siguiente la automatización saldrá en la dirección opuesta a aquel en que ha notado el obstáculo. Si en lógica automática la cancela intenta partir para 3 veces a la cuarta vez quedará abierta y la lámpara quedará encendida. Después la cuarta intervención consecutiva será necesario un start para conseguir el restablecimiento del movimiento.

Nota: El control de la inversión sobre obstaculizo habrá hasta el logro del final de carrera.

### **Atención:**

**En caso de falla de alimentación con fines de carrera y Encoder activos la primera maniobra ocurrirá sin control de inversión sobre obstáculo hasta el logro del final de carrera de abertura.**



## PROGRAMACIÓN RADIOCOMANDOS

**! CUIDADO:** para efectuar la programación de los emisores, es necesario haber conectado la antena e insertado el receptor en su conector CMR (el cuadro reconocerá automáticamente si el receptor es un módulo RF, RF ROLL, RF ROLL PLUS o RF UNI). Con el módulo RF Roll o RF Roll Plus será posible utilizar solo emisores Mariquita Roll o Mariquita Roll Plus o bien Smart Dual Roll o Smart Dual Roll Plus. Con módulo RF UN será posible utilizar sea radiocomandos de la serie Roll Plus como radiocomandos a código fijo. El primer radiocomando memorizado determinará la tipología de los restantes radiocomandos.

### **Nota:**

- Efectuar la programación de emisores solo con puerta detenida.
- Si los radiocomandos son Rolling Codes o Rolling Code Plus es posible memorizar hasta 800 códigos (pulsantes).
- Si los radiocomandos son a código fijo será posible memorizar hasta un máximo de 30 códigos (pulsantes).

**Nota:** en todos los modelos de RF, los transmisores HEAD son memorizados como código fijo.

### **Autoapprendissaje del start de un transmisor**

- 1) Oprimir el pulsante P2 por tres segundos, los led 1 y 2 relampaguearan alternativamente.
- 2) Pisar P1 para seleccionar el led1, luego comprimir P2 (el led1 quedará encendido fijo), para confirmar la elección y pisar el interruptor del radiocomando a que se quiere asociar el start. El led1 se apaga, señal adquirida.

### **Autoapprendissaje del start peatonal de radiocomando**

- 1) Oprimir P2 por tres segundos, los led 1 y 2 relampaguearan alternativamente.
- 2) Oprimir P1 por 2 veces, para seleccionar el led2, luego comprimir P2 (el led2 quedará encendido fijo) para confirmar la elección y pisar el interruptor del radiocomando a que se quiere asociar el start peatonal. El led1 se apaga, señal adquirida.

### **Cancelacion de todos los transmisores**

- 1) Oprimir el pulsante P2 por tres segundos, los led 1 y 2 relampagueran alternativamente.
- 2) Teniendo oprimido P1, oprimir tres veces el pulsante P2.



## **ADVERTENCIAS**

Cada modifica sobre trimmers debe ser efectuada con puerta cerrada o sin alimentación eléctrica.

La instalación eléctrica y la lógica de funcionamiento deben estar de acuerdo con la normativa vigente. Preveer en cada caso un interruptor diferencial puesto al inicio de la instalación eléctrica de la automación de 16A y umbral de intervención de 0,030A. Tener separados los cables de potencia (motor, alimentaciones etc.) de los de mando (pulsadores, fotocélulas, receptores radio etc.). Para evitar interferencias es preferible preveer y utilizar al menos dos váinas separadas.

## **REPUESTOS**

Los pedidos de repuestos tienen que ser enviados a:

**SEA USA Inc. 10850 N.W. 21st unit 160 DORAL MIAMI Florida (FL) 33172 USA**

**Phone:++1-305.594.1151 Fax: ++1-305.594.7325 Toll Free: 800.689.4716**

**E-mail: sales@sea-usa.com**

## **UTILIZACION**

La maniobra electrónica SLIDE ha sido proyectada para ser utilizada exclusivamente como tarjeta de mando para la automatización de cancelas corredizas.

## **CONDICIONES DE GARANTIA**

Por la garantía se vean las Condiciones de venta indicadas en el catálogo oficial SEA.

**N.B. EL FABRICANTE NO PUEDE SER CONSIDERADO RESPONSABLE POR EVENTUALES DAÑOS ACARREADOS POR USO IMPROPIO, ERRONEO Y IRRAZONABLE.**

## Details

### General

An appliance shall be provided with an instruction manual. The instruction manual shall give instructions for the installation, operation, and user maintenance of the appliance.

The installation instructions shall specify the need for a grounding-type receptacle for connection to the supply and shall stress the importance of proper grounding.

The installation instructions shall inform the installer that permanent wiring is to be employed as required by local codes, and instructions for conversion to permanent wiring shall be supplied.

Information shall be supplied with a gate operator for:

- a) The required installation and adjustment of all devices and systems to effect the primary and secondary protection against entrapment (where included with the operator).
- b) The intended connections for all devices and systems to effect the primary and secondary protection against entrapment. The information shall be supplied in the instruction manual, wiring diagrams, separate instructions, or the equivalent.

### Vehicular gate operators (or systems)

A vehicular gate operator shall be provided with the information in the instruction manual that defines the different vehicular gate operator Class categories and give examples of each usage. The manual shall also indicate the use for which the particular unit is intended as defined in Glossary, Section 3. The installation instructions for vehicular gate operators shall include information on the Types of gate for which the gate operator is intended.

A gate operator shall be provided with the specific instructions describing all user adjustments required for proper operation of the gate. Detailed instructions shall be provided regarding user adjustment of any clutch or pressure relief adjustments provided. The instructions shall also indicate the need for periodic checking and adjustment by a qualified technician of the control mechanism for force, speed, and sensitivity.

Instructions for the installation, adjustment, and wiring of external controls and devices serving as required protection against entrapment shall be provided with the operator when such controls are shipped with the operator.

Instructions regarding intended installation of the gate operator shall be supplied as part of the installation instructions or as a separate document. The following instructions or the equivalent shall be supplied where applicable:

- a) Install the gate operator only when:
  - 1) The operator is appropriate for the construction of the gate and the usage Class of the gate,
  - 2) All openings of a horizontal slide gate are guarded or screened from the bottom of the gate to a minimum of 4 feet (1.22 m) above the ground to prevent a 2-1/4 inch (57.2 mm) diameter sphere from passing through the openings anywhere in the gate, and in that portion of the adjacent fence that the gate covers in the open position,
  - 3) All exposed pinch points are eliminated or guarded, and
  - 4) Guarding is supplied for exposed rollers.
- b) The operator is intended for installation only on gates used for vehicles. Pedestrians must be supplied with a separate access opening. The pedestrian access opening shall be designed to promote pedestrian usage. Locate the gate such that persons will not come in contact with the vehicular gate during the entire path of travel of the vehicular gate.
- c) The gate must be installed in a location so that enough clearance is supplied between the gate and adjacent structures when opening and closing to reduce the risk of entrapment. Swinging gates shall not open into public access areas.
- d) The gate must be properly installed and work freely in both directions prior to the installation of the gate operator. Do not over-tighten the operator clutch or pressure relief valve to compensate for a damaged gate.
- e) (not applicable)
- f) Controls intended for user activation must be located at least six feet (6') away from any moving part of the gate and where the user is prevented from reaching over, under, around or through the gate to operate the controls. Outdoor or easily accessible controls shall have a security feature to prevent unauthorized use.

g) The Stop and/or Reset button must be located in the line-of-sight of the gate. Activation of the reset control shall not cause the operator to start.

h) A minimum of two (2) WARNING SIGNS shall be installed, one on each side of the gate where easily visible.

i) For gate operators utilizing a non-contact sensor:

- 1) See instructions on the placement of non-contact sensors for each Type of application,
- 2) Care shall be exercised to reduce the risk of nuisance tripping, such as when a vehicle, trips the sensor while the gate is still moving, and
- 3) One or more non-contact sensors shall be located where the risk of entrapment or obstruction exists, such as the perimeter reachable by a moving gate or barrier.

j) For a gate operator utilizing a contact sensor:

- 1) One or more contact sensors shall be located where the risk of entrapment or obstruction exists, such as at the leading edge, trailing edge, and postmounted both inside and outside of a vehicular horizontal slide gate.
- 2) One or more contact sensors shall be located at the bottom edge of a vehicular vertical lift gate.
- 3) One or more contact sensors shall be located at the pinch point of a vehicular vertical pivot gate.
- 4) A hardwired contact sensor shall be located and its wiring arranged so that the communication between the sensor and the gate operator is not subjected to mechanical damage.
- 5) A wireless contact sensor such as one that transmits radio frequency (RF) signals to the gate operator for entrapment protection functions shall be located where the transmission of the signals are not obstructed or impeded by building structures, natural landscaping or similar obstruction. A wireless contact sensor shall function under the intended end-use conditions.
- 6) One or more contact sensors shall be located on the inside and outside leading edge of a swing gate. Additionally, if the bottom edge of a swing gate is greater than 6 inches (152 mm) above the ground at any point in its arc of travel, one or more contact sensors shall be located on the bottom edge.
- 7) One or more contact sensors shall be located at the bottom edge of a vertical barrier (arm).

Revised 56.8.4 effective February 21, 2008

Instruction regarding intended operation of the gate operator shall be provided as part of the user instructions or as a separate document. The following instructions or the equivalent shall be provided:

#### **IMPORTANT SAFETY INSTRUCTIONS**

**WARNING** – To reduce the risk of injury or death:

1. READ AND FOLLOW ALL INSTRUCTIONS.
2. Never let children operate or play with gate controls. Keep the remote control away from children.
3. Always keep people and objects away from the gate. **NO ONE SHOULD CROSS THE PATH OF THE MOVING GATE.**
4. Test the gate operator monthly. The gate **MUST** reverse on contact with a rigid object or stop when an object activates the non-contact sensors. After adjusting the force or the limit of travel, retest the gate operator. Failure to adjust and retest the gate operator properly can increase the risk of injury or death.
5. Use the emergency release only when the gate is not moving.
6. **KEEP GATES PROPERLY MAINTAINED.** Read the owner's manual. Have a qualified service person make repairs to gate hardware.
7. The entrance is for vehicles only. Pedestrians must use separate entrance.
8. **SAVE THESE INSTRUCTIONS.**





**SEA USA Inc.**  
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